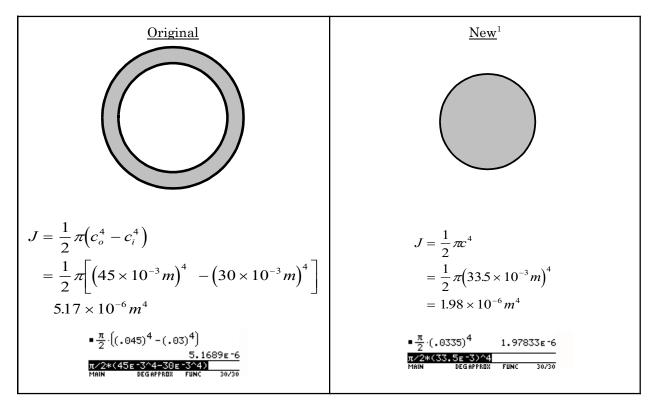


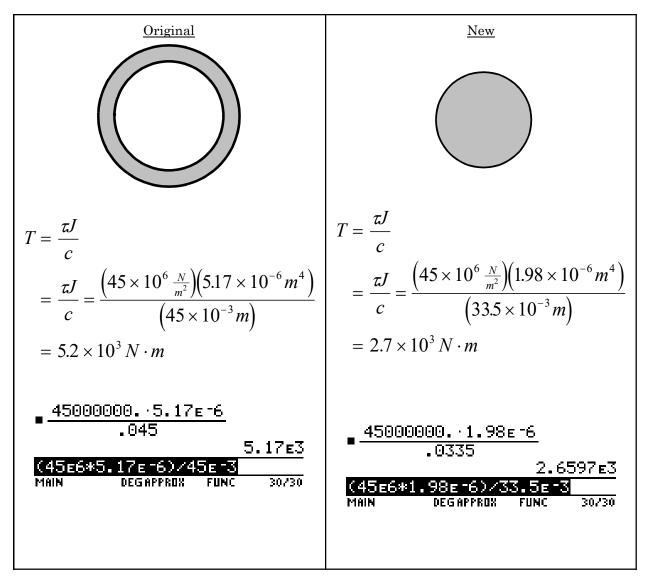
This problem requires that you examine the effect of changing the Polar Moment of Inertia (J)



The maximum torque can be determined as follows.

$$\tau = \frac{Tc}{J}$$
$$T = \frac{\tau J}{c}$$

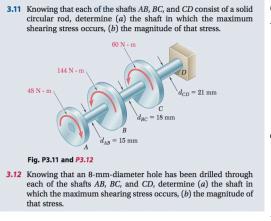
¹Please note that this is based on maintaining cross sectional area. Please contact me if the calculation of the new radius 33.5mm is unclear.



The shear stress at the surface of the new cylinder is:

$$\tau = \frac{T_c}{J} = \frac{(5.2 \times 10^3 \, N \cdot m)(33.5 \times 10^{-3} \, m)}{(1.98 \times 10^{-6} \, m^4)} = 88 \times 10^6 \frac{N}{m^2}$$

= $\frac{5200 \cdot \cdot 0335}{1.98 \cdot 6}$
= $\frac{5200 \cdot \cdot 0335}{1.98 \cdot 6}$



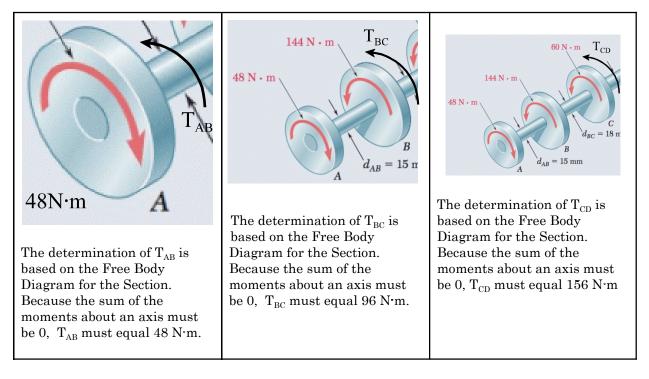
Given that the maximum shear stress in each rod, that is the stress at the surface is:

$$\tau = \frac{Tc}{J} = T\frac{2}{\pi c^3} = T\frac{16}{\pi d^3}$$

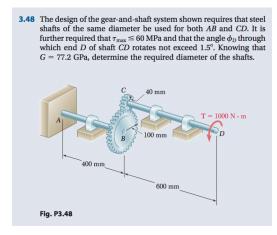
Thus, $\frac{16}{\pi d^3}$ is a geometrical factor for each of the shafts.

For AB this is
$$\frac{16}{\pi (15 \times 10^{-3} m)^3} = 1.5 \times 10^6 m^{-3}$$
.

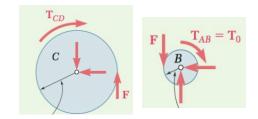
For BC this is $870 \times 10^3 \text{m}^{-3}$, and for CD this is $550 \times 10^3 \text{m}^{-3}$.



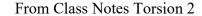
The shear stresses for the three shafts are: For $AB = 72 \times 10^6 \text{ N/m}^2$ For $BC = 84 \times 10^6 \text{ N/m}^2$ For $CD = 86 \times 10^6 \text{ N/m}^2$



It is necessary to calculate the torque in each shaft. T_{CD} can be determined as the sum of the moments must equal 0. T_{CD} =1000N·m. However the total force at the interface between the gears must be 0. This was shown in our exploration of Sample Problem 3.4.



This means that,



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ince the shafts are going to have the same diameter it is only necessary to determine the required diameter for CD. Based on the formula for shear stress at the surface of a shaft.

 $T_{CD} = T_{AB} \frac{r_c}{r_B} = 2.5 T_{AB}$

 $T_{AB} = r_B F$

 $T_{CD} = r_c F$

 $\frac{T_{AB}}{r_B} = \frac{T_{CD}}{r_c}$

$$\tau_{\rm max} = \frac{Tc}{J}$$

The following formula can be determined

$$\frac{J}{c} = \frac{T}{\tau_{\rm max}} = \frac{1}{2} \pi c^3$$

This means,

$$c^3 = \frac{2}{\pi} \frac{T}{\tau_{\text{max}}}$$

c can then be calculated as shown,

$$c = \sqrt[3]{\frac{2}{\pi} \frac{T}{\tau_{\text{max}}}} = \sqrt[3]{\frac{2}{\pi} \frac{1000 N \cdot m}{60 \times 10^6 \frac{N}{m^2}}} = 22 \times 10^{-3} m$$

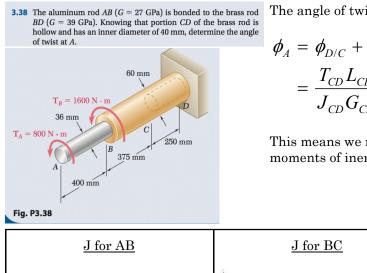
$$= \left(\frac{\frac{2}{\pi} \cdot 1000}{60000000}\right)^{1/3}$$

$$= \frac{1}{\sqrt{2\pi \times 1000 \times 60 \times 60 \times 10^{-3} \text{ m}^{-3}}}$$

The angle of twist at D will be

$$\begin{split} \phi_{D} &= \phi_{C} + \phi_{C/D} \\ \phi_{C} &= \frac{r_{C}}{r_{B}} \phi_{B} \\ &= \frac{r_{C}}{r_{B}} \frac{T_{AB} L_{AB}}{JG} \\ &= \frac{r_{C}}{r_{B}} \frac{T_{0} L_{AB}}{JG} \\ &= \frac{T_{0} L_{AB}}{JG} + \frac{T_{0} L_{CD}}{JG} \\ \phi_{D} &= \frac{T_{0} L_{AB}}{JG} + \frac{T_{0} L_{CD}}{JG} \\ &= \frac{T_{0}}{JG} (L_{AB} + L_{CD}) \\ J &= \frac{T_{0}}{\phi_{D}G} (L_{AB} + L_{CD}) \\ c^{4} &= \frac{2}{\pi} \frac{T_{0}}{\phi_{D}G} (L_{AB} + L_{CD}) \\ c &= \sqrt{\frac{2}{\pi} \frac{T_{0}}{\phi_{D}G} (L_{AB} + L_{CD})} \\ &= \sqrt{\frac{2}{\pi} \frac{T_{0}}{\phi_{D}G} (L_{AB} + L_{CD})} \\ &= \sqrt{\frac{2}{\pi} \frac{T_{0}}{(26 \times 10^{-3} rad) (77.2 \times 10^{9} \frac{N}{m^{2}})} (400 \times 10^{-3} m + 600 \times 10^{-3} m) \\ c &= 23.8 \times 10^{3} m \end{split}$$

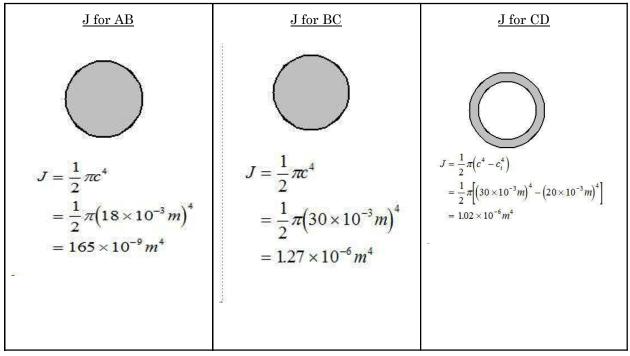
The required diameter is 48mm ($48x10^{-3}$ m)



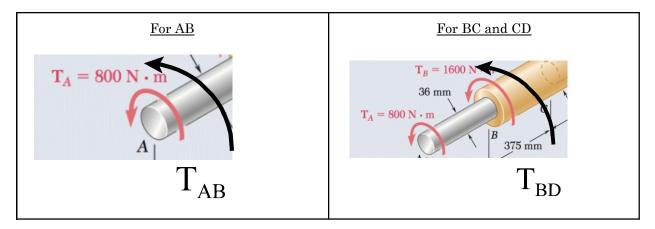
The angle of twist at A will be,

$$\phi_{A} = \phi_{D/C} + \phi_{C/B} + \phi_{B/A}$$
$$= \frac{T_{CD}L_{CD}}{J_{CD}G_{CD}} + \frac{T_{BC}L_{BC}}{J_{BC}G_{BC}} + \frac{T_{AB}L_{AB}}{J_{AB}G_{AB}}$$

This means we need to determine the torques and polar moments of inertia J for each section.



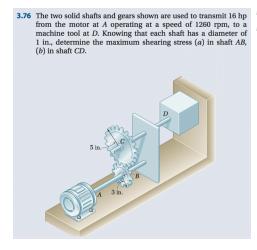
The torques within each member must be determined based on the total moment about any axis must be zero. These will be determined by sectioning as shown below.



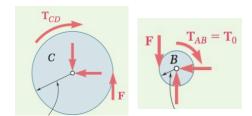
Thus the three torques are

- •
- $T_{AB} = 800 \text{N·m}$ $T_{BC} = 2400 \text{N·m}$ $T_{CD} = 2400 \text{N·m}$ •

$$\begin{split} \phi_{A} &= \phi_{D/C} + \phi_{C/B} + \phi_{B/A} \\ &= \frac{T_{CD} L_{CD}}{J_{CD} G_{CD}} + \frac{T_{BC} L_{BC}}{J_{BC} G_{BC}} + \frac{T_{AB} L_{AB}}{J_{AB} G_{AB}} \\ &= \frac{(2400N \cdot m)(250 \times 10^{-3} m)}{(1.02 \times 10^{-6} m^{4})(39 \times 10^{9} \frac{N}{m^{2}})} + \frac{(2400N \cdot m)(375 \times 10^{-3} m)}{(1.27 \times 10^{-6} m^{4})(39 \times 10^{9} \frac{N}{m^{2}})} + \frac{(800N \cdot m)(400 \times 10^{-3} m)}{(0.165 \times 10^{-6} m^{4})(27 \times 10^{9} \frac{N}{m^{2}})} \\ &= 0.105rad = 6 \deg \end{split}$$



The total force at the interface between the gears must be 0. This was shown in our exploration of Sample Problem 3.4.



From Class Notes Torsion 2

This means that,

$$T_{AB} = r_B F$$

$$T_{CD} = r_c F$$

$$\frac{T_{AB}}{r_B} = \frac{T_{CD}}{r_c}$$

$$T_{CD} = T_{AB} \frac{r_c}{r_B} = T_{AB} \frac{5in}{3in} = 1.7 T_{AB}$$

Since the torque in AB is due to the power.

$$T = \frac{P}{2\pi f}$$

= $\frac{1600hp}{2\pi (1260rpm)} = \frac{52.8 \times 10^6 \frac{ft \cdot lb}{min}}{2\pi (1260 \frac{1}{min})}$
 $6.57 \times 10^3 ft \cdot lb$

Because the diameter of both rods are 1 inch, J and c will be equal for both. Since,

$$\tau = \frac{Tc}{J}$$
$$\tau_{CD} = 1.7 \tau_{AB}$$

For shaft AB,

$$c^{3} = \frac{2}{\pi} \frac{T}{\tau_{\text{max}}}$$
$$\tau_{\text{max}} = \frac{2}{\pi} \frac{T}{c^{3}}$$
$$= \frac{2}{\pi} \frac{74.8 \times 10^{3} \text{ in} \cdot lb}{(0.5 \text{ in})^{3}}$$
$$= 380 \times 10^{3} \text{ psi}$$

For shaft CD this will be $646 \times 10^3 psi$